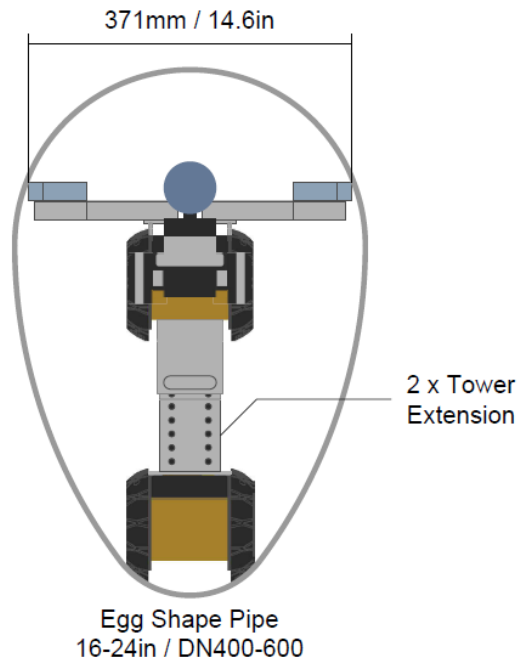
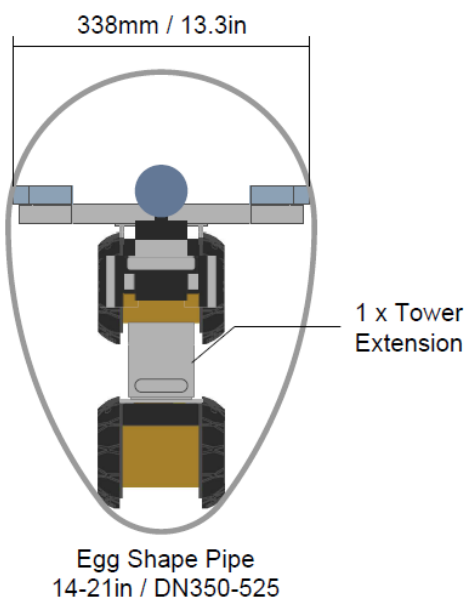
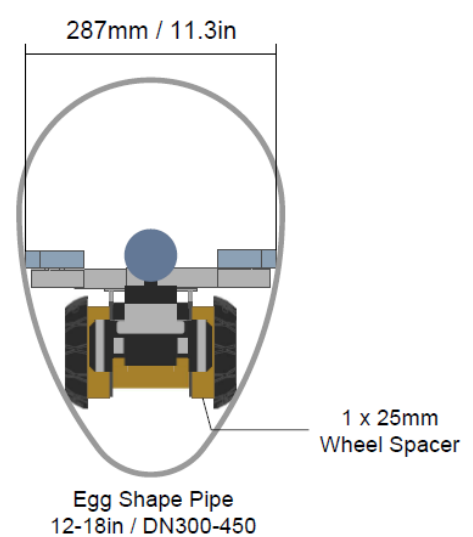
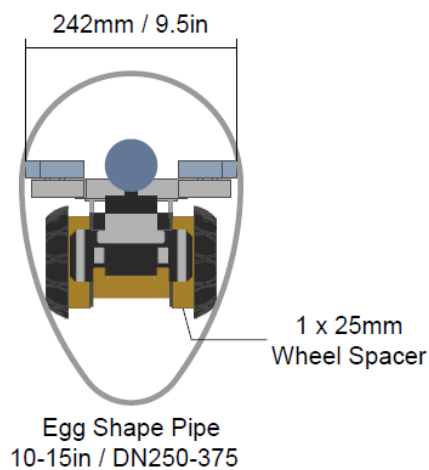
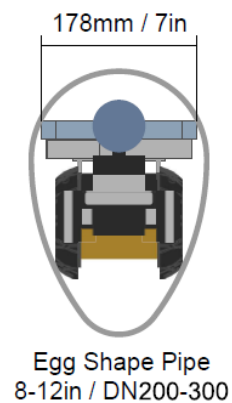




This document contains suggestions for configuring the egg shape pipe robot carriage designed for the Talpa FSR 2060. The carriage system includes a bracket for securing the Talpa FSR 2060, individually mountable tower extensions, and the carriage tower. The modular design of the tower extensions allows for adjustable positioning of the robot at the required height to navigate various egg shape pipe profiles effectively.

For operation, the digital box of the Talpa FSR 2060 connects to the control cable on the oval pipe robot carriage, with the carriage's connector mounted onto the digital box position. This configuration separates control commands between the oval pipe carriage's drive functions and the Talpa FSR 2060's camera and robot arm movements.

Please refer to the following diagrams and instructions to ensure proper setup and sizing for optimal performance in egg shape pipe conditions.





SCHWALM
ROBOTIC

CARRIAGE DIAGRAM FOR EGG SHAPE PIPE

